

A Probabilistic Approach for Identifying Faulty Node in Mobile Wireless Network

Spoorthi¹, H P Mohan Kumar²

^{1,2}MCA department, PES College of engineering Mandya

Abstract-In this paper, the main aim of this work is to identifying the failure nodes and strengths of the nodes in the network, we have used two approach's for this one is localized monitoring and combination of location estimation and node collaboration to identifying the failure node and failure area in the network irrespective of connected or disconnected network. In first approach, When one node cannot hear from a nearest Node, it uses its own information about nearest node and binary feedback from its nearest node to make decision whether the node has failed or active, in second approach it gathers the information and make a decisions, first approach incurs lower communication than second approach. The second approach utilizes all gather information from nearest node and give better performance.

Keywords-Mobile wireless network, Network monitoring, Node failure, Fault management.

I. INTRODUCTION

For establishing the communication we will form a network using network topology. communication like transfer data from one node to another node, here the node is a terminal, also can acts as a interface between two or more networks by connecting the networks. Mobile wireless networks have been used for many mission critical applications, including search and rescue, environment monitoring disaster relief, and military operations [3]. These mobile networks are usually formed in an ad-hoc form, with either lasting or irregular network connectivity. Nodes in these networks are [endangered](#) to failures due to battery discharge, hardware problem or a rasping environment. Detecting failure node in the mobile wireless network is most important and difficult, because network structure will be very dynamic that means nodes will be in movement. It is even more difficult when the moving devices are carried by person and are used for the communication mechanism. In such cases the technologies designed for fixed network will not applies for above situation. Secondly, it is not applicable for disconnected network because network cannot be always connected. Thirdly, limited resources. Identifying failure node in mobile wireless networks presumes network connectivity. Many approaches choose "heartbeat" or adopt probe-and-ACK based techniques that are regularly used in distributed computing.

These techniques require a central monitor for transferring a probe messages to other nodes. Once the source node get to know that the destination node is not responding with replay message with in a timeout interval, the central monitor decides that node is not active. Heartbeat based techniques different from probe-and-ACK based techniques in that for limiting the amount of messages they destroy the probing phase. Many existing studies choose gossip based protocols, where a node receiving a gossip message on node failure details, and combines its information with the received information, and then relay the merged information. There is a drawback of probe-and-ACK, heartbeat and gossip based techniques is they are only applicable to connected networks. And also they requires a large amount of network-wide monitoring traffic. But in our approach is applicable to both connected and disconnected networks and only generates localized monitoring traffic.

In existing system they have adopted centralized monitoring approach. In this, node send periodic "heartbeat" messages to central monitor, this central monitor decides whether the node is active or not if the destination node replay back to central monitor then central monitor will conclude that the node is active otherwise it assumes the node is failure. This approach assumes that there will be always exists a path from central monitor to a node and hence the lasting connectivity is only applicable. we cannot find whether the node is strong or not in existing system. While transfer of data when it finds the failure node it just inform the details of failure node and it stops. it won't finds the alternative node to continue the data transformation. Another one is Localized monitoring will only generates the localized traffic and used successfully for node failure detection in static networks.

II. RELATED WORK

Most existing reviews on hub disappointment identification in portable remote systems expect arrange network. Many plans [6], [1], [5] embrace test and-ACK (i.e., ping) or pulse based procedures that are normally utilized as a part of appropriated registering [4], [6]. Test and-ACK based methods require a focal screen to send test messages to different hubs. At the point when a hub does not answer inside a timeout interim, the focal screen views the hub as fizzled. Pulse based strategies vary from test and-ACK based

procedures in that they dispose of the examining stage to diminish the measure of messages. A few existing reviews [3], [6] embrace chatter based conventions, where a hub, after getting a babble message on hub disappointment data, blends its data with the data got, and afterward communicates the consolidated data. A typical downside of test[3] and ACK, pulse and talk based procedures is that they are just pertinent to systems that are associated. What's more, they prompt a lot of system wide observing traffic. Interestingly, our approach just produces limited observing traffic and is material to both associated and disengaged systems. The plan in [1] utilizes restricted checking. It is, in any case, not reasonable for portable systems since it doesn't consider that inability to get notification from a hub may be because of hub portability rather than hub disappointment. Our approach considers f hub versatility. To the best of our insight, our approach is the first that exploits area data to identify hub disappointments in versatile systems. As other related work, the investigation of [2] identifies obsessive discontinuity accepting that it takes after a two-state Markov show, which may not hold by and by. The investigation of [2] confines arrange interface disappointments with a high overhead: it utilizes occasional pings to acquire end-to-end disappointment data between each combine of hubs, uses intermittent traceroutes to get the present system topology, and afterward transmits the disappointment and topology data to a focal site for conclusion.

III. PROPOSED SYSTEM

In proposed system we have introduced a new approach along with the localized monitoring and combination of location estimation and node collaboration to identify the faulty nodes in mobile wireless network and the complete implementation of the proposed approach is described in the below flow chart(Fig 1) which gives complete view of this work.Simulation results demonstrate that both schemes achieve high failure detection rates, low false positive rates, and incur low communication overhead. Our approach has the advantage that it is applicable to both connected and disconnected networks. Compared to other approaches that use localized monitoring, our approach has similar failure detection rates, lower communication overhead and much lower false positive rate. Our approach only generates localized monitoring traffic and is applicable to both connected and disconnected networks. The system architecture shown in the (Fig 2) represent the complete architecture of the proposed work.

FLOW CHART



Fig 1: Flow Chart

SYSTEM ARCHITECTURE

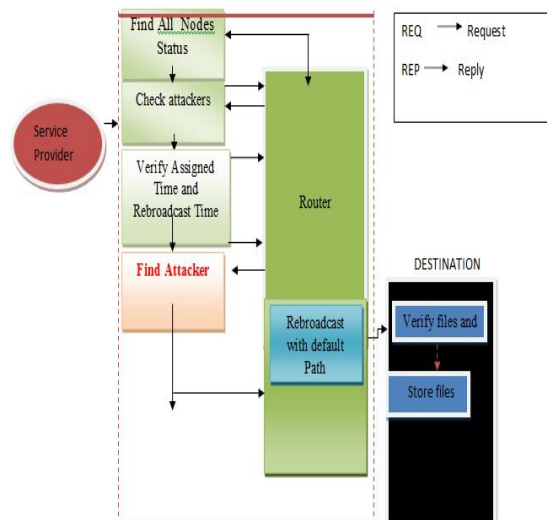


Fig 3: System Architecture

IV. APPROACH

Let us consider an example figure (Fig2) given below to discuss our approach. At time t , all the nodes are active, and node N_1 can hear the periodic heartbeat messages from N_2 and N_3 . At time $t+1$, node N_2 fails and N_3 goes out of N_1 's transmission range (Fig2). By localized monitoring, N_1 can only analyse that it can no longer hear periodic messages from N_2 and N_3 , but it cannot analyse whether the non-existence of messages is due to failure of node or node is crossed out of the transmission range. To overcome from these problems, location estimation is helpful: through the location estimation, N_1 knows the probability that N_2 is within its transmission range, finds that the probability is high, and hence conjectures that the absence of messages from N_2 is due to N_2 's failure; similarly, N_1 obtains the probability that N_3 is within its transmission range, finds that the probability is low, and hence conjectures that the absence of messages from N_3 is because N_3 is out of the transmission range. The above work can be improved through node collaboration. Here, N_1 can broadcast an inquiry about N_2 to its one-hop neighbours at time $t + 1$, and use the response from N_4 to either confirm or correct its conjecture about N_2 . The above example indicates that it is important to structurally combine localized monitoring, location estimation and node collaboration, which is the fundamental of our approach. The main aim of our approach is to calculate node failure probability. Assume that a node, A , hears the periodic heartbeat packets from another node B , at times $t - k, \dots, t(k \geq 0)$, but not at time $t + 1$. We next derive the probability that node B has failed at time $t+1$ given the fact that node A can no longer hear B at $t+1$. In the following, the node failure probability is for node B , and the packet loss probability is for the heartbeat packet from B to A at $t+1$.

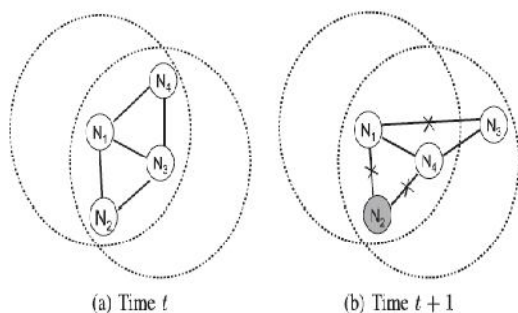


Fig 2

V. RESULT AND DISCUSSION

The centralised monitoring approach used to detect node failure in mobile wireless network, it is only applicable for static network and connected network, in this node sends

periodic “heartbeat” messages to central monitor, this central monitor decides whether the node is active or not if the destination node replay back to central monitor then central monitor will conclude that the node is active otherwise it assumes that the node is failure. In proposed work the approaches location estimation and node collaboration combines together to produce better performance, it is applicable for both connected and disconnected network, and achieves high failure detection rates, low false positive rates, and low communication overhead. In this approaches it gathers the information and make a decisions, and when the node is failure it finds the alternative path to reach or transfer the data to the destination due to this the lack of data can be avoided. In some cases node can be moved to out of transmission range because nodes will be highly dynamic by this proposed approach we are overcome from these all problems.

VI. CONCLUSION

The proposed work introduced a probabilistic approach and designed two approaches for identifying the failure node that combine localized monitoring, location estimation and node collaboration for mobile wireless networks. This results shows that our approaches achieve, low false positive rates, high failure detection rates, and low communication overhead. The proposed approach completely depends on the usage of periodic heartbeat messages and location estimation for nodes to make decision on node failure and monitor each other. Therefore, when location information is not available it does not work or there is failure in communication due to weather conditions and one important advantage of this approach while data is transferring from one node to another if the node is failure it will find the alternative path to reach the destination, this is done by location estimation and node collaboration.

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