A TWO-LEVEL LES CONSTRUCTED WITH UNFILTERED EQUATIONS AND SGS MODELS OF PHYSICAL VARIABLES

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CURRENT OFTEN-STUDIED FORMS OF LES

- Smagorinsky—it's easy and efficient, relatively at least
- Combinations of LES and RANS—*e.g.*, DES
- Dynamic Models—produce backscatter; hence able to transition
- Implicit LES, *e.g.*, MILES—do not filter equations of motion
- "Synthetic-Velocity" Models in General, e.g., estimation models, LEM, ODT—all utilize subgrid-scale (SGS) models based on physical variables





A NOT-TOO-DIFFERENT ALTERNATIVE

- Basically a Synthetic-Velocity Model Constructed Using the Following Ideas
 - Filter solutions rather than equations—just implementation of *mollification* from pure PDE theory
 - <u>Model sub-grid physical variables</u> instead of their statistics—one approach is use "*symbols*" of the differential operators
 - <u>Directly use SGS results</u> to enhance large-scale (deliberately under-resolved) part—analogous to a *multi-level* formalism
- Most of These Already Being Used in One or More of Typical Approaches, But Usually Not All Applied Simultaneously
- Some Details on Each Follow





FILTERING

 Why Filter Anything?—LES resolved-scale solutions under resolved and will alias

- Filtering equations produces terms whose models provide dissipation
- Filtering solutions is easier, and more easily analyzed—just mollification in pure-math sense; eliminate high-frequency/high-wavenumber components leading to nonsmoothness
- How? define C^{∞} function $u_{\epsilon}(x,t)$ as $u_{\epsilon}(x,t) = \int_{-\epsilon}^{\epsilon} u(\xi,t) \,\delta_{\epsilon}(x-\xi) \,d\xi$, where δ_{ϵ} is C_{0}^{∞} with support in $[-\epsilon,\epsilon]$
 - Error easily determined for most practical filters
 - Essentially same form of filter usually applied to equations of motion
- Where, When?—at all points of resolved-scale grid, and for every time step





FILTERING (Cont.)

- Present Approach Utilizes Shuman Filter Formally Derived From Mollifier Shown Above (McDonough & Yang, in preparation)
- Basic Discrete Form:

$$\widetilde{u}_{i}(\boldsymbol{x},t) = \frac{\beta u_{i} + \sum_{j \in S_{i}} u_{j}}{\beta + 2^{d}},$$

where $\beta \in (-2^d, \infty)$ is filter parameter; *i*, *j* are multi-indices of dimension *d*; S_i is index set of nearest neighbors of *i*

- Can be shown to provide needed dissipation as required for mollification
- Solution shown at right requires minimum 4096 points for stable DNS, but can be computed using only 512 points with filtering
- Leads to global (in time) first-order accuracy with overall results comparable to those obtained using Smagorinsky model of classical LES







SUBGRID-SCALE MODELS

- Typical Models Are Statistical; *i.e.*, they model <u>velocity</u> <u>correlations</u>
- Seems Difficult (and expensive) to Model Dependent Variables on Sub-Grid Scales
- But There Are (at least) Several Alternatives
 - Use only high-wavenumber terms of local Fourier representation—one of many approaches to low-dimensional models, but generally still too expsive in 3D
 - Use 1-D equations on sub-grid scales—but raises numerous fundamental questions; examples include LEM and ODT of Kerstein and coworkers
 - Employ local (in each large-scale grid cell) formulations based on discrete dynamical systems (DDSs)—the approach to be considered here
 - not too different from shell models—hence, very low dimensional locally, but still contains considerable global information (unlike a shell model)
 - can be constructed directly from governing equations





ALTERNATIVE FORM OF SGS MODEL

Model Takes Form

$$q_i^* = A_i M_i$$

- $q_i^* i^{th}$ component of small-scale solution vector
- A_i amplitude determined from "extended" Kolmogorov theory
- $M_i i^{th}$ component of discrete dynamical system (DDS) consisting of equations for velocity components and any associated scalars
- Details of Computing A_i s
 - Based on <u>local</u> in space and time "on-the-fly" analysis of 2nd-order structure functions for each small-scale variable:

$$S_{2,i}(r) \equiv \left\langle \left[\check{q}_{i}(\boldsymbol{x}+\boldsymbol{r}) - \check{q}_{i}(\boldsymbol{x})\right]^{2}\right\rangle$$

- \check{q}_i high-pass filtered large-scale q_i
- $\langle \cdot \rangle$ average over all neighboring grid points of x at distance r = |r|





CALCULATION OF AMPLITUDES (Cont.)

- Extension of these formulas to case of anisotropic turbulence achieved by replacing 2/3 exponent with arbitrary (but computed) one, and similarly for the Kolmogorov constant
 - results in general power laws: $S_{2,i}(r) = C_{2,i}(\langle \varepsilon \rangle r)^{\beta}$
 - exponent and constant computed locally in space and time
 - figures show snapshot (in time) of one horizontal plane of LES of fire whirl: (a) exponent, (b) constant
 - note that exponent would be ~2/3 (yellow) in regions of flow associated with the inertial subrange
- Finally, observe that <u>amplitude</u> A_i is just $|| q_i^* || \Rightarrow$ by Parseval's identity

$$A_i = \left(\sum_k E(k)\right)^{1/2}$$







THE DISCRETE DYNAMICAL SYSTEMS

- Details of Computing M_i s
 - *M_i* s provide small-scale <u>temporal</u> <u>fluctuations</u>
 - Obtained starting with "projection-method form" of N.–S. equations:

$$\boldsymbol{U}_t + \boldsymbol{U} \cdot \nabla \boldsymbol{U} = \boldsymbol{v} \Delta \boldsymbol{U}$$

where, in 2-D, $U = (u, v)^T$

• Assume Fourier representations for velocity components (and also for all scalars), *e.g.*,

$$u^{*}(\mathbf{x},t) = \sum_{k=-\infty}^{\infty} a_{k}(t) \varphi_{k}(\mathbf{x}) \qquad \qquad v^{*}(\mathbf{x},t) = \sum_{k=-\infty}^{\infty} a_{k}(t) \varphi_{k}(\mathbf{x})$$

where $\{\varphi_k\}$ is orthonormal with properties analogous to complex exponentials *wrt* differentiation



DISCRETE DYNAMICAL SYSTEMS (Cont.)

• Apply <u>Galerkin procedure</u>, and decimate result to single wavevector in each equation

$$\dot{a}_{k} + A_{k\ell m}^{(1)} a_{k}^{2} + A_{k\ell m}^{(2)} a_{k} b_{k} = -\frac{|k|^{2}}{Re} a_{k}$$
$$\dot{b}_{k} + B_{k\ell m}^{(1)} b_{k}^{2} + B_{k\ell m}^{(2)} a_{k} b_{k} = -\frac{|k|^{2}}{Re} b_{k}$$

- $A_{k\ell m}^{(i)}$, etc. contain Galerkin triple products and wavevector components associated with Fourier representation of velocity gradients
- wavevector k selected to correspond to Taylor microscale
- Use simple <u>forward-Euler</u> <u>time</u> <u>integration</u> with time step *τ*, and suppress subscripts

$$a^{(n+1)} = a^{(n)} - \tau \left[\frac{|k|^2}{Re} a^{(n)} + A^{(1)} (a^{(n)})^2 + A^{(2)} a^{(n)} b^{(n)} \right]$$
$$b^{(n+1)} = b^{(n)} - \tau \left[\frac{|k|^2}{Re} b^{(n)} + B^{(1)} (b^{(n)})^2 + B^{(2)} a^{(n)} b^{(n)} \right]$$



DISCRETE DYNAMICAL SYSTEMS (Cont.)

 Motivated by Frisch's epithet "poor man's Navier-Stokes" equation when referring to a generic quadratic map, and the fact that any such map can be transformed to the well-understood logistic map, we transform each of the above by setting

$$\tau A^{(1)} = 1 - \tau \frac{|k|^2}{Re}$$

and defining

$$\beta_1 \equiv 4\left(1 - \tau \frac{|k|^2}{Re}\right)$$
 and $\gamma_1 \equiv \tau A^{(2)}$

• With analogous definitions associated with the second of the above equations, we obtain the 2-D poor man's N.–S. (PMNS) equations:

$$a^{(n+1)} = \beta_1 a^{(n)} \left(1 - a^{(n)} \right) - \gamma_1 a^{(n)} b^{(n)}$$
$$b^{(n+1)} = \beta_2 b^{(n)} \left(1 - b^{(n)} \right) - \gamma_2 a^{(n)} b^{(n)}$$



PMNS EQUATIONS

• 2-D PMNS equations studied extensively

- McDonough & Huang, Int. J. Numer. Meth. Fluids (2004)
- McDonough *et al.*, J. Turbulence (2003)
- Bible & McDonough, Int. J. Bifurcation and Chaos (2004)
- 14 possible states identified, as indicated in figure at right
- Figure also displays potential of PMNS eqs. undergoing many different bifurcation sequences including the well-known ones

Steady → Periodic → Quasiperiodic → Chaotic
Steady → Periodic → Subharmonic → Chaotic
Steady → Periodic → Intermittent → Chaotic







PMNS EQUATIONS (Cont.)

- observe that β_i s are directly related to *Re*, a wavevector and a time scale—all of which are readily computed
- figures to right display contours of β (part a) and γ (part b) in a single horizontal plane of a 3-D firewhirl simulation
- schematic of computational domain shown below









PMNS EQUATIONS (Cont.)

- PMNS equations also have been fit to experimental data by Yang *et al.*, *AIAA J.* (2003) using fractal least-squares algorithm first introduced by McDonough *et al.*, *Appl. Math. Comput.* (1998)
 - corresponds to flow behind backward-facing step





- Treatment extended to thermal convection (both free and forced) by McDonough & Joyce (2002) and by McDonough *et al.* (2005) in preparation
 - experiments due to Gollub & Benson, JFM (1980)
 - DDS results obtained with only <u>single</u> realization of PMNS + thermal energy equations





MULTI-LEVEL FORMALISM

- LES Intrinsically Multilevel—but not usually implemented to reflect this
- Consider LES Decomposition of Dependent Variables:

 $\boldsymbol{Q}(\boldsymbol{x},t) = \boldsymbol{\overline{q}}(\boldsymbol{x},t) + \boldsymbol{q}'(\boldsymbol{x},t)$

- Viewed as consisting of "large-" and "small-scale" parts
- But usually only <u>effects of small scale</u> are modeled—not the small-scale variables themselves
- Synthetic-Velocity Models Are the Exception
 - In implementing these we may—or, may not—be faced with now recognized mathematical difficulties of correctly combining large- and smallscale parts
 - Approach reported here imposes requirement of <u>numerical consistency</u> of complete algorithm with differential equations being solved





SAMPLE CALCULATIONS

- Several Standard Turbulence Test Problems Have Been Run (but have not been completely analyzed)
 - Decay of isotropic turbulence in $2\pi^3$ periodic box
 - initial Taylor microscale Reynolds number $Re_{\lambda} \sim 150$
 - result computed on 16³ grid
 - required only minutes to obtain energy spectrum close to that of Huang & Leonard (1997) computed on 256³ grid
 - colors represent small-scale fluctuating vorticity (red ~ high positive, blue ~ high negative)
 - vortices smaller than grid scale created by SGS model



- 3-D channel flow with four solid walls, periodicity in streamwise direction
- 3-D backward-facing step flow with <u>no</u> periodic directions





SAMPLE CALCULATIONS (Cont.)

- Two Physical Problems Simulated to Date—both involving natural convection in addition to flow field
 - Simulation of laboratory fire whirl experiment
 - computational domain shown earlier consists of laboratory 3 m on a side and 3 m high with 1 m² × 1.6 m high fire-whirl generating apparatus having 0.1 m slots in each corner



- grid employed was rather coarse 61 × 61 × 41
- figure at right displays resolved-scale and fluctuating time series of two velocity components and temperature







SAMPLE CALCULATIONS (Cont.)

• Simulated Forest Fire Spread

- 7 km x 1.5 km x 2 km (vertical) with approximately 50 m x 50 m horizontal grid spacing
- Side view of fire after 10 min ➡



- Streamlines of fluctuating velocity field colored with small-scale vorticity magnitude
- Parallel speedup →

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FOREST FIRE SIMULATION (Cont.)

 Zoomed View of Fire Spread Showing More Details of Temperature Fluctuations and Fire Whirls







SUMMARY

- Slightly Different LES Alternative Presented
 - Based on filtering solutions, modeling physical variables and explicitly combining large- and small-scale parts
 - Each part of process has sound mathematical basis—but connecting all the pieces is nontrivial
- Preliminary a priori tests suggest SGS model generally works well
 - Has successfully identified turbulent and non-turbulent flow regions in quite complicated flow fields including buoyancy effects
 - Able to generate small-scale structures below grid scale—and do this very efficiently with no adjustable parameters except those used in filter
- Open Questions Remain Concerning Coupling of Large- and Small-Scale Parts
- Results for Fundamental Problems Have Yet to Be Thoroughly Analyzed—so they are, in a sense, still anecdotal



