

SCAN 2002

Affine Arithmetic: Concepts and Applications

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- What is affine arithmetic?
- The dependency problem in interval arithmetic
- Main concepts in affine arithmetic
- Comparing affine arithmetic with interval arithmetic
- Exploiting the correlations given by affine arithmetic
- Other approaches to the dependency problem

• AA is a tool for validated numerics

◊ introduced by Comba and Stolfi in 1993

- AA is designed to handle the dependency problem in IA
 - ◊ AA keeps track of *first-order correlations*
- AA has been used successfully as a replacement for interval arithmetic
 - ◊ AA provides tighter interval estimates in many cases
 - ◊ AA provides additional information that can be exploited

IA can't see correlations between operands

$$g(x) = (10 + x)(10 - x) \text{ for } x \in [-2, 2]$$

$$10 + x = [8, 12]$$

$$10 - x = [8, 12]$$

$$(10 + x)(10 - x) = [64, 144] \quad \text{diam} = 80$$
Exact range = [96, 100] \quad \text{diam} = 4



IA can't see correlations between operands

$$g(x) = (10 + x)(10 - x) \text{ for } x \in [-u, u]$$

$$10 + x = [10 - u, 10 + u]$$

$$10 - x = [10 - u, 10 + u]$$

$$(10 + x)(10 - x) = [(10 - u)^{2}, (10 + u)^{2}] \quad \text{diam} = 40u$$

$$\text{Exact range} = [100 - u^{2}, 100] \quad \text{diam} = u^{2}$$



$$g(x) = \sqrt{x^2 - x + 1/2} / \sqrt{x^2 + 1/2}$$



g

 $g \circ g$

 $g^n \rightarrow c =$ fixed point of $g \approx 0.5586$, but intervals diverge

Interval estimates may get too large in long computations

Affine arithmetic: concepts

AA represents a quantity x with an *affine form*

$$\hat{x} = x_0 + x_1 \varepsilon_1 + \dots + x_n \varepsilon_n$$

- noise symbols $\varepsilon_i \in \mathbf{U} = [-1, +1]$ independent, but otherwise unknown
- central value $x_0 \in \mathbf{R}$
- partial deviations $x_i \in \mathbf{R}$
- n is not fixed

new noise symbols created during computation

Affine forms imply interval bounds:

$$x \sim \hat{x} = x_0 + x_1 \varepsilon_1 + \dots + x_n \varepsilon_n \Rightarrow x \in [x_0 - r, x_0 + r]$$

$$r = |x_1| + \dots + |x_n| \text{ is the total deviation of } \hat{x}$$

Conversely,

$$x \in [a, b]$$
$$x \sim \hat{x} = x_0 + x_1 \varepsilon_1$$
$$x_0 = (b+a)/2$$
$$x_1 = (b-a)/2$$

AA algorithms can input and output intervals, but affine forms give more information.

Affine forms that share noise symbols are not independent:

$$\hat{x} = x_0 + x_1\varepsilon_1 + \dots + x_n\varepsilon_n$$
$$\hat{y} = y_0 + y_1\varepsilon_1 + \dots + y_n\varepsilon_n$$

The region containing (x, y) is

$$Z = \{(x, y) : \varepsilon_i \in \mathbf{U}\}$$

This region is the image of \mathbf{U}^n under an affine map $\mathbf{R}^n \rightarrow \mathbf{R}^2$. It's a centrally symmetric convex polygon, a *zonotope*.



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The region would be a rectangle if x and y were independent.



• Affine operations are straightforward by design:

$$\hat{x} \pm \hat{y} = (x_0 \pm y_0) + \dots + (x_n \pm y_n)\varepsilon_n$$

$$\alpha \hat{x} = (\alpha x_0) + (\alpha x_1)\varepsilon_1 + \dots + (\alpha x_n)\varepsilon_n$$

$$\hat{x} \pm \alpha = (x_0 \pm \alpha) + x_1\varepsilon_1 + \dots + x_n\varepsilon_n$$

• For non-affine operations, use good affine approximation and append extra term to represent error:

$$\widehat{f} = f_0 + f_1 \varepsilon_1 + \dots + f_n \varepsilon_n + f_k \varepsilon_k$$

(new noise symbol created)

• Add new noise noise symbol on each operation (affine or not) to account for rounding errors.

To compute z = f(x, y), when f is not an affine operation, write:

$$f(x,y) = f(\hat{x},\hat{y})$$

= $f(x_0 + x_1\varepsilon_1 + \dots + x_n\varepsilon_n, y_0 + y_1\varepsilon_1 + \dots + y_n\varepsilon_n)$
= $f^*(\varepsilon_1,\dots,\varepsilon_n)$

where $f^*: \mathbf{U}^n \to \mathbf{R}$. Now approximate

$$f^*(\varepsilon_1,\ldots,\varepsilon_n) = f^{\mathsf{a}}(\varepsilon_1,\ldots,\varepsilon_n) + z_k \varepsilon_k$$

where f^{a} is some affine approximation of f^{*} with error bounded by z_{k} :

$$\left|f^*(\varepsilon) - f^{\mathsf{a}}(\varepsilon)\right| \le |z_k| \quad \text{for all } \varepsilon \in \mathrm{U}^n$$

Easiest to take $f^a = \alpha \hat{x} + \beta \hat{y} + \gamma$. (Exact for univariate operations.)

$$\hat{z} = \hat{f}(\hat{x}, \hat{y}) = z_0 + z_1 \varepsilon_1 + \dots + z_n \varepsilon_n + z_k \varepsilon_k$$

$$\hat{x} \cdot \hat{y} = (x_0 + \sum_{i=1}^n x_i \varepsilon_i) \cdot (y_0 + \sum_{i=1}^n y_i \varepsilon_i)$$

= $x_0 y_0 + \sum_{i=1}^n (x_0 y_i + y_0 x_i) \varepsilon_i + \sum_{i=1}^n x_i \varepsilon_i \cdot \sum_{i=1}^n y_i \varepsilon_i$

So
$$\hat{x} \cdot \hat{y} = x_0 y_0 + \sum_{i=1}^n (x_0 y_i + y_0 x_i) \varepsilon_i + z_k \varepsilon_k$$
, where

$$|z_k| \ge \left|\sum_{i=1}^n x_i \varepsilon_i \cdot \sum_{i=1}^n y_i \varepsilon_i\right|, \qquad \varepsilon_i \in \mathbf{U}$$

Easiest to take

$$z_k = \sum_{i=1}^n |x_i| \cdot \sum_{i=1}^n |y_i|$$

Choice of affine approximations



Chebyshev

Minimum range

- Chebyshev minimizes error best approximation
- Minimum range minimizes range :-) preserves signs
- Both have quadratic approximation errors



Comparing AA with IA: The dependency problem

The dependency problem in interval arithmetic – AA version

AA can see correlations between operands

$$g(x) = (10 + x)(10 - x) \text{ for } x \in [-u, u], \qquad x = 0 + u\varepsilon$$

$$10 + x = 10 - u\varepsilon$$

$$10 - x = 10 + u\varepsilon$$

$$(10 + x)(10 - x) = 100 - u^{2}\varepsilon$$

$$\text{range} = [100 - u^{2}, 100 + u^{2}] \qquad \text{diam} = 2u^{2}$$

$$\text{Exact range} = [100 - u^{2}, 100] \qquad \text{diam} = u^{2}$$



The dependency problem in interval arithmetic – AA version

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$$g(x) = (10 + x)(10 - x) \text{ for } x \in [-u, u], \qquad x = 0 + u\varepsilon$$

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$$(10 + x)(10 - x) = 100 - u^{2}\varepsilon$$

$$\text{range} = [100 - u^{2}, 100 + u^{2}] \qquad \text{diam} = 2u^{2}$$

$$\text{Exact range} = [100 - u^{2}, 100] \qquad \text{diam} = u^{2}$$





Comparing AA with IA: Examples in computer graphics

 $x^{2} + y^{2} + xy - (xy)^{2}/2 - 1/4 = 0$



IA (246 cells, 66 exact)

(70 cells) AA

Tensor product Bézier surfaces of degree (p,q):

$$f(u,v) = \sum_{i=0}^{p} \sum_{j=0}^{q} a_{ij} B_i^p(u) B_j^q(v), \quad B_i^n(t) = \binom{n}{i} t^i (1-t)^{n-i}$$







Surface intersection – domain decompositions



AA

Exploiting the correlations given by AA





Solution:

- Write $\gamma(t) = (x(t), y(t))$.
- Represent $t \in T$ with an affine form:

$$\hat{t} = t_0 + t_1 \varepsilon_1, \qquad t_0 = (b+a)/2, \quad t_1 = (b-a)/2$$

• Compute coordinate functions x and y at \hat{t} using AA:

$$\hat{x} = x_0 + x_1\varepsilon_1 + \dots + x_n\varepsilon_n$$
$$\hat{y} = y_0 + y_1\varepsilon_1 + \dots + y_n\varepsilon_n$$

• Use bounding rectangle of the *xy* zonotope.









Approximating parametric curves











IA (32 boxes)

(8 boxes) AA Rotated rectangles computed from AA zonotopes • Implicit surface

$$h: \mathbf{R}^3 \to \mathbf{R}$$
$$S = \{p \in \mathbf{R}^3 : h(p) = 0\}$$

- Ray $r(t) = E + t \cdot v, \quad t \in [0, \infty)$
- Ray intersects S when f(t) = h(r(t)) = 0
- First intersection occurs at *smallest* zero of f in $[0, \infty)$.
- Paint pixel with color based on normal at first intersection point



- Implicit surface
 - $h: \mathbf{R}^3 \to \mathbf{R}$ $S = \{p \in \mathbf{R}^3 : h(p) = 0\}$
- Ray $r(t) = E + t \cdot v, \quad t \in [0, \infty)$
- Ray intersects S when f(t) = h(r(t)) = 0
- First intersection occurs at *smallest* zero of f in $[0, \infty)$.
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 $4(x^4 + (y^2 + z^2)^2) + 17x^2(y^2 + z^2) - 20(x^2 + y^2 + z^2) + 17 = 0$

• Solve f(t) = 0 using inclusion function F for f:

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F(T) \supseteq f(T) = \{f(t) : t \in T\}, \quad T \subseteq I
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- $0 \notin F(T) \Rightarrow no \text{ solutions of } f(t) = 0 \text{ in } T$
- $0 \in F(T) \Rightarrow$ there *may* be solutions in *T*

```
interval-bisection([a, b]):

if 0 \in F([a, b]) then

c \leftarrow (a + b)/2

if (b - a) < \varepsilon then

return c

else

interval-bisection([a, c]) \leftarrow try left half first!

interval-bisection([c, b])
```

Start with interval-bisection ($[0, t_{\infty}]$) to find the *first* zero.

Ray casting implicit surfaces with affine arithmetic

- AA exploits linear correlations of x, y, z in f(t) = h(r(t))
- AA provides additional information
 - ◊ root must lie in smaller interval
 - ◊ quadratic convergence near simple zeros





Conclusion

- AA useful replacement for IA
 - $\diamond~$ AA more accurate than IA
 - ◊ AA provides additional information that can be exploited
 - ◊ AA locally more expensive than IA but globally more eficient
- AA algorithms not always faster
 - ◊ AA overestimates squares if implemented naively
 - ◊ AA range estimates not always better
- AA has geometric flavor
 - ◊ good for computer graphics!

- Generalized interval arithmetic (Hansen, 1975)
 - affine expressions on a fixed set of "noise symbols" with *interval* coefficients
 - ◊ affine operations *not* exact
 - does not exploit direct correlations of intermediate values
- Linear interval arithmetic (Tupper, 1996) basis of GrafEq
- Centered forms
- Slopes
- Taylor forms (Berz)
- Zonotope enclosures (Kühn, 1998)
 - ◊ AA is zonotope arithmetic!

- "A Numerical Method of Proving the Existence of Solutions for Nonlinear ODEs Using Affine Arithmetic", by Yuchi Kanzawa and Shin'ichi Oishi (yesterday at 12:00)
- "Interval Arithmetic, Affine Arithmetic, Taylor Series Methods: Why? What Next?", by Nedialko Nedialkov, Vladik Kreinovich, and Scott Starks (today at 11:00)