Graphs Connectivity Directed and Undirected Graphs

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Outline

- Some terminologies
- Testing Connectivity of Graphs
 - Directed graph
 - Undirected graph
- Related work
 - Undirected bounded graph
 - Directed graph
- Other kind of tester.
- Summary

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- Topic: Testing Connectivity of Graphs
- Author: Hsuan Chang Chen
- Source: Master thesis, Graduate Institute of Computer Science and Information Engineering, NTU, 2006.

Property Tester I

Definiton

A **Tester** T for property P is an algorithm for given ϵ and input x,

Property Tester II

 Query complexity: We aim at spending time that is sublinear in or even independent of the size of graph.

- Distance function d(·, ·) Hamming dist., Edit dist. etc.
 - ▶ *ϵ*-close
 - ▶ *ϵ*-far

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Testing Connectivity of Graphs I.

- How to solve this problem?
- What is the time complexity?
- Good enough?

Testing Connectivity of Graphs II.

Graph representation matters!

- Is the former algorithm good for adjacent matrix?
- Is the former algorithm good for adjacent linked list?
- What are the suitable algorithms for such graph representations?

Testing Connectivity of Graphs III.

- Graph representation matters for property testing, too!
 - for adjacent matrix?
 - for adjacent linked list?
- It is not trivial! Different graph representation might make the same problem un-testable.

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Testing Connectivity of Graphs VI.

Related Work

- ▶ Goldreich et. al., 1997[4], 2002[5]
 O (^{log²(1/εd)}/_ε), Undirected bounded degree model.
- Blender et. al., 2000[1], 2002[2] $\Omega(\sqrt{n})$, adjacency matrix.
- Chen's Contributions
 - On adjacency matrix
 - No restriction on degree.
 - Time complexity $O\left(\frac{1}{\epsilon \log(1-\epsilon)}\right)$

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For Undirteced Graphs I.



Figure: The disconnected graph and connected components

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For Undirteced Graphs II.



Figure: The connected graph with as spanning tree of connected components

For Undirteced Graphs III.

Lemma

- If a graph G, is ϵ -far from the class of connected graphs, then it has more than $\epsilon \binom{n}{2}$ connected components.
- Thus its distance measure is

 $\frac{\# \text{ of adding edges}}{\# \text{ of edges of } K_n}$

For Undirteced Graphs IV.



Figure:
$$\binom{11}{2} = 55, 55 \times \epsilon = 3, \therefore \epsilon = \frac{3}{55}$$
.

For Undirteced Graphs V.

Lemma

If a graph G, is ϵ -far from the class of connected graphs, then it has at least ϵ n connected components each containning less than $\lceil \frac{2}{n-3}(\frac{1}{\epsilon}-1) \rceil$ vertices.

For Undirteced Graphs VI.

Proof.

Assume it is wrong



For Undirteced Graphs VII.

Roughly speaking, we want to find some small connected components as the evidence of disconnectivity.

Algorithm

- ► $S \leftarrow \emptyset, M \leftarrow \lceil \log_{1-\epsilon} \frac{1}{3} \rceil, X \leftarrow \lceil \frac{2}{n-3} (\frac{1}{\epsilon} 1) \rceil$
- While |S| < M do
 - pick u from V then add it to S. Perform BFS from u and stop as reach X vertices or run out of vertices (REJECT)



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For Undirteced Graphs VIII.

Theorem

If a graph G is connectivity, then it must accept. If G is ϵ -far from the class of connected graphs, then it has reject with probability at least $\frac{2}{3}$. The query complexity and time complexity are $O(\frac{1}{\epsilon \log(1-\epsilon)})$. Obviously it is one-side error:

$$P \leq (1-\epsilon)^{\lceil \log_{1-\epsilon}rac{1}{3}
ceil} \leq rac{1}{3}$$

For Undirteced Graphs IX.

Since it costs *n* to find all neighbors on adjacency matrix for each vertex, we have time complexity:

$$\lceil \log_{1-\epsilon} \frac{1}{3} \rceil \cdot \lceil \frac{2}{n-3} (\frac{1}{\epsilon} - 1) \rceil \cdot n$$

$$< \left[\frac{1}{\log_{\frac{1}{3}} (1-\epsilon)} + 1 \right] \cdot \left[\frac{2}{n-3} (\frac{1}{\epsilon} - 1) + 1 \right] \cdot n$$

$$= O\left(\frac{1}{\epsilon \log(1-\epsilon)}\right)$$

For Digraphs I.

Recall some terminolgies of Digraph

- strongly connected: ∀u, v ∈ V, ∃ a directed path u → v in G,
- source: node with only out-degree,
- sink: node with only in-degree,
- isolation: node without in-degree and out-degree,
- transferrer: node with in-degree and out-degree,

If a graph G, is ϵ -far from the class of strongly connected graphs, then the number of source, sink, and isolation components in G will be larger than ϵn^2 . Note: Chen assumed that all components are strongly connected.

For Digraphs III.

The idea of proof is similar to undirected one. if no **transferrer**, the case is the following





Figure: strongly connected components without transferrers

Figure: As directed cycle of strongly connected components

For Digraphs IV.

If **transferrers** exist, the case is the follwoing





Figure: strongly connected components of several types

If a graph G, is ϵ -far from the class of strongly connected graphs, then it has at least ϵ n strongly connected components each containing less than $\left\lceil \frac{1}{n-2}(\frac{1}{\epsilon}-1) \right\rceil$ vertices.

For Digraphs VI.

Proof. Assume it is wrong

$$n \geq \{\epsilon n^{2} + 1 - \epsilon n\} \cdot \left\lceil \frac{1}{n-2} (\frac{1}{\epsilon} - 1) \right\rceil + \epsilon n$$

> $(\epsilon n^{2} - \epsilon n) \cdot \frac{1}{n-2} (\frac{1}{\epsilon} - 1) + \epsilon n$
= $\frac{n-1}{n-2} (n - \epsilon n) + \epsilon n$
> $(n - \epsilon n) + \epsilon n$

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Roughly speaking, we want to find some small connected components as the evidence of disconnectivity.

But we need to check two directions, in-degree and out-degree.

Algorithm

►
$$S \leftarrow \varnothing, M \leftarrow \lceil \log_{1-\epsilon} \frac{1}{3} \rceil, X \leftarrow \lceil \frac{1}{n-2} (\frac{1}{\epsilon} - 1) \rceil$$

• While |S| < M do

- pick u from V then add it to S. Perform BFS from u using in-degree and stop as reach X vertices or run out of vertices (REJECT)
- Ìf it reach X vertices
 - Perform BFS from u using out-degree and stop as reach X vertices or run out of vertices (REJECT)



Why do we need to check two directions?



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For Digraphs VIII.

Theorem

If a digraph G is connectivity, then it must accept. If G is ϵ -far from the class of connected graphs, then it has reject with probability at least $\frac{2}{3}$. The query complexity and time complexity are $O(\frac{1}{\epsilon \log(1-\epsilon)})$. Obviously it is one-side error:

$$P \leq (1-\epsilon)^{\lceil \log_{1-\epsilon} rac{1}{3}
ceil} \leq rac{1}{3}$$

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For Digraphs IX.

Since it costs *n* to find all neighbors on adjacency matrix for each vertex, we have time complexity:

$$\lceil \log_{1-\epsilon} \frac{1}{3} \rceil \cdot 2 \cdot \lceil \frac{1}{n-2} (\frac{1}{\epsilon} - 1) \rceil \cdot n$$

$$< [\frac{1}{\log_{\frac{1}{3}} (1-\epsilon)} + 1] \cdot [\frac{2}{n-2} (\frac{1}{\epsilon} - 1) + 2] \cdot n$$

$$= O(\frac{1}{\epsilon \log(1-\epsilon)})$$

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Is Chen's algorithm a property tester?

For given undirected disconnected graph G(V, E), |V| = n, |E| = m, one add k − 1 edges to make G connected, therefore

$$\epsilon \binom{n}{2} = \epsilon \frac{n(n-1)}{2} = k$$

$$\epsilon = \frac{2(k)}{n(n-1)} \le \frac{2}{n}$$

It is not independent from input.

Some questions!





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What's the contribution of previous wroks?

 Goldreich et. al., 1997[4], 2002[5]. Their algorithm could test the *k*-connectivity, and in $O\left(\frac{\log^2(1/\epsilon d)}{\epsilon}\right)$ for k = 1 on bounded degree model. • dist $(G, P) = 2\rho_d(G, P)/dn$, i.e., $\rho_d(G, P)$ the edit distance to closest connected graph P. イロン スロン スロン スロン 二日

Goldreich et. al. 2002



Figure: bounded degree model

Goldreich et. al. 2002

Connectivity Testing Algorithm

- 1 For *i* from 1 to $\log(8/(\epsilon d))$ do:
 - Uniformly and independently select
 m_i = 32 log(8/(εd))/(2ⁱ ⋅ ε ⋅ d) vertices
 in the graph.
 - For each vertex s selected, perform a BFS starting from s until 2ⁱ vertices have been reached or no more new vertices can be reached (REJECT).

2 ACCEPT.

Let $d \ge 2$. If a graph G is ϵ -far from the class of n-vertex connected graphs with maximum degree d, then it has more than $(\epsilon/4)$ dn connected components.

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If a graph G is ϵ -far from the class of n-vertex connected graphs of degree bound $d \ge 2$, then G has at least $dn\epsilon/8$ connected components each containing less than $8/(d\epsilon)$ vertices.

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If G is ϵ -far from the class of connected graphs with maximum degree d, then Algorithm rejects it with probability at least 2/3. The query complexity and running time of the algorithm are $O\left(\frac{\log^2(1/\epsilon d)}{\epsilon}\right)$

PROOF:

Since it is ϵ -far, there are at least $dn\epsilon/8$ connected components. Let B_i be the set of connected components in G which contain at most $2^i - 1$ vertices and at least 2^{i-1} vertices.

The probability that a uniformly selected vertex resides in one of these components is at least

$$\frac{2^{i-1}|B_i|}{n} \ge \frac{2^{i-1}}{n} \frac{dn\epsilon}{(8\log(8/(\epsilon d)))} = \frac{2}{m_i}$$

Thus $1 - (1 - \frac{2}{m_i})^{m_i} \ge 1 - e^{-2} \ge \frac{2}{3}$.

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Roughly speaking, for each turn,

$$egin{aligned} O(m_i imes ext{Time}_{BFS}) &= 32 rac{\log(rac{8}{\epsilon d})}{(2^i \cdot \epsilon \cdot d)} \cdot 2^i d \ &= rac{32 \log(rac{8}{\epsilon d})}{\epsilon} \end{aligned}$$

, Thus it costs
$$O\left(\frac{\log^2(1/\epsilon d)}{\epsilon}\right)$$
.
End of Proof

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Blender et. al. proposed two algorithms for testing connectivity on digraph.

1 The informations of outgoing edges and incoming edges of a vertex are available.

Note that Chen's algorithm for digraph is this type.

2 Only the information of outgoing edges of a vertex is available.

- The first one is very similar to Chen's algorithm, but it is based on bounded degree graph
- The time complexity is in $O(\frac{1}{\epsilon^2 d})$,
- Chen found a better "small size"

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Is the ϵ independent from *G*? No!

Goldreich: $\epsilon \frac{dn}{2} \leq n-1 \Rightarrow \epsilon < \frac{2}{d}, \epsilon \frac{dn}{2} \geq 1 \Rightarrow \epsilon \geq \frac{2}{dn}$ $O\left(\frac{\log^2(1/\epsilon d)}{\epsilon}\right) \Rightarrow \left(\frac{d\log^2(d)}{2}\right), dn\log^2(\frac{n}{2})$

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Review the Property Tester

- Property tester behaves as an algorithm with constant parameter ϵ .
- Chen's ϵ is not independent, too!
- Does there exist indepednet tester?

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Q: Dose a sequence be sorted?

- Any deterministic decision algorithm runs in Ω(n) to read the input and make a decision.
- Ergun et. al. 2000[3] proposed an algorithm to solve it in sublinear time.

Monotonicity Testing Algorithm

- For j from 1 to $O(1/\epsilon)$ do:
 - Query x_i from sequence x₁x₂···x_n, uniformly at random.
 - Perform binary search for x_i. If the search does not found x_i, return "No".



- Their algorithm runs in time O(^{log n}/_e) since each binary search costs O(log n).
 It is in BPP
- ϵ -far for ϵn elements that BSearch fails,
- $(1-\epsilon)^{c/\epsilon} < e^{c/\epsilon} < 1/3$ for some c
- ϵ is independent from *n*.

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Summary

- Graph representations,
- Randomized sampling,
- Query complexity,Oblivious Tester[6]
- Parameter e matters! Decision version PTAS?



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