

On the Parameterized Complexity for Token Jumping on Graphs^{*}

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Abstract. Suppose that we are given two independent sets I_0 and I_r of a graph such that $|I_0| = |I_r|$, and imagine that a token is placed on each vertex in I_0 . Then, the TOKEN JUMPING problem is to determine whether there exists a sequence of independent sets which transforms I_0 into I_r so that each independent set in the sequence results from the previous one by moving exactly one token to another vertex. Therefore, all independent sets in the sequence must be of the same cardinality. This problem is PSPACE-complete even for planar graphs with maximum degree three. In this paper, we first show that the problem is W[1]-hard when parameterized only by the number of tokens. We then give an FPT algorithm for general graphs when parameterized by both the number of tokens and the maximum degree. Our FPT algorithm can be modified so that it finds an actual sequence of independent sets between I_0 and I_r with the minimum number of token movements.

1 Introduction

The TOKEN JUMPING problem was introduced by Kamiński *et al.* [13], which can be seen as a “dynamic” version of independent sets in a graph. Recall that an

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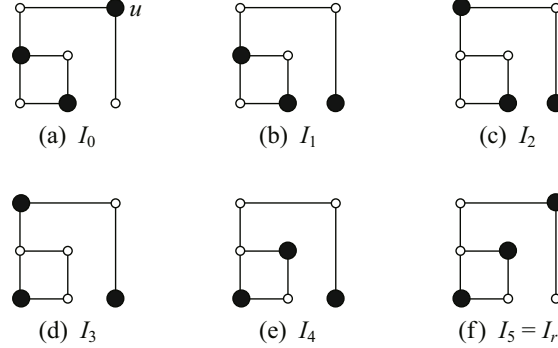


Fig. 1. A sequence $\langle I_0, I_1, \dots, I_5 \rangle$ of independent sets of the same graph, where the vertices in independent sets are depicted by large black circles (tokens)

independent set of a graph G is a vertex-subset of G in which no two vertices are adjacent. (See Fig. 1 which depicts six different independent sets of the same graph.) Suppose that we are given two independent sets I_0 and I_r of a graph $G = (V, E)$ such that $|I_0| = |I_r|$, and imagine that a token (coin) is placed on each vertex in I_0 . Then, the TOKEN JUMPING problem is to determine whether there exists a sequence $\langle I_0, I_1, \dots, I_\ell \rangle$ of independent sets of G such that

- (a) $I_\ell = I_r$, and $|I_i| = |I_0| = |I_r|$ for all i , $1 \leq i \leq \ell$; and
- (b) for each index i , $1 \leq i \leq \ell$, I_i can be obtained from I_{i-1} by moving exactly one token on a vertex $u \in I_{i-1}$ to another vertex $v \in V \setminus I_{i-1}$, and hence $I_{i-1} \setminus I_i = \{u\}$ and $I_i \setminus I_{i-1} = \{v\}$.

Figure 1 illustrates a sequence $\langle I_0, I_1, \dots, I_5 \rangle$ of independent sets which transforms I_0 into $I_r = I_5$.

Recently, this type of problems have been studied extensively in the framework of *reconfiguration problems* [8], which arise when we wish to find a step-by-step transformation between two feasible solutions of a problem such that all intermediate solutions are also feasible and each step abides by a prescribed reconfiguration rule (*i.e.*, an adjacency relation defined on feasible solutions of the original problem). For example, the TOKEN JUMPING problem can be seen as a reconfiguration problem for the (ordinary) INDEPENDENT SET problem: feasible solutions are defined to be all independent sets of the same cardinality in a graph; and the reconfiguration rule is defined to be the condition (b) above. This reconfiguration framework has been applied to several well-known problems, including INDEPENDENT SET [5,6,8,13,15], SATISFIABILITY [4,14], SET COVER, CLIQUE, MATCHING [8], VERTEX-COLORING [1,2,3], LIST EDGE-COLORING [9,11], LIST $L(2,1)$ -LABELING [10], SUBSET SUM [7], SHORTEST PATH [12], etc.

1.1 Reconfiguration Rules and Related Results

The original reconfiguration problem for INDEPENDENT SET was introduced by Hearn and Demaine [5], which employs another reconfiguration rule. Indeed,

there are three reconfiguration problems for INDEPENDENT SET (ISRECONF, for short) under different reconfiguration rules, as follows.

- **Token Sliding (TS)** [2,5,6,13]: We can slide a single token only *along an edge* of a graph. In other words, each token can be moved only to its adjacent vertex. This rule corresponds to the original one introduced by Hearn and Demaine [5].
- **Token Jumping (TJ)** [13]: This rule corresponds to TOKEN JUMPING, that is, we can move a single token to any vertex.
- **Token Addition and Removal (TAR)** [8,13,15]: We can either add or remove a single token at a time if it results in an independent set of cardinality at least a given threshold. Therefore, independent sets in the sequence do not have the same cardinality.

We remark that the existence of a desired sequence depends deeply on the reconfiguration rules. For example, Fig. 1 is an yes-instance for TOKEN JUMPING, but it is a no-instance for ISRECONF under the TS rule.

We here explain only the results which are strongly related to TOKEN JUMPING; see the references above for the other results.

Hearn and Demaine [5], [6, Sec. 9.5] proved that ISRECONF under the TS rule is PSPACE-complete for planar graphs of maximum degree three. Then, Bonsma and Cereceda [2] showed that this problem remains PSPACE-complete even for very restricted instances. Indeed, their result implies that TOKEN JUMPING is PSPACE-complete for planar graphs with maximum degree three. (Details will be given in Section 2.3.)

Kamiński *et al.* [13] proved that ISRECONF is PSPACE-complete for perfect graphs under any of the three reconfiguration rules. As the positive results for TOKEN JUMPING, they gave a linear-time algorithm for even-hole-free graphs. Furthermore, their algorithm can find an actual sequence of independent sets with the minimum number of token movements.

1.2 Our Contributions

In this paper, we investigate the parameterized complexity of the TOKEN JUMPING problem.

We first show that the problem is W[1]-hard when parameterized only by the number t of tokens. Therefore, the problem admits no FPT algorithm when parameterized only by t unless $\text{FPT} = \text{W}[1]$.

We thus consider the problem with two parameters, and give an FPT algorithm for general graphs when parameterized by both the number of tokens and the maximum degree. Recall that the problem remains PSPACE-complete even if the maximum degree is three. (See Section 2.3.) Therefore, it is very unlikely that the problem can be solved in polynomial time even for graphs with bounded maximum degree.

Finally, we show that our FPT algorithm for general graphs can be modified so that it finds an actual sequence of independent sets between I_0 and I_r with

the minimum number of token movements. We remark that the sequence of independent sets in Fig. 1 has the minimum length. It is interesting that the token on the vertex u in Fig. 1(a) must be moved twice even though $u \in I_0 \cap I_r$.

2 Preliminaries

In this section, we first introduce some basic terms and notations which will be used throughout the paper. We then formally show the PSPACE-completeness of TOKEN JUMPING in Section 2.3.

2.1 Graph Notations

In TOKEN JUMPING, we may assume without loss of generality that graphs are simple. For a graph G , we sometimes denote by $V(G)$ and $E(G)$ the vertex set and the edge set of G , respectively. Let $n(G) = |V(G)|$ and $m(G) = |E(G)|$. We denote by $\Delta(G)$ the maximum degree of G .

For a vertex v of a graph G , we denote by $N(G; v)$ the set of all neighbors of v in G (which does not include v itself), that is, $N(G; v) = \{w \in V(G) \mid (v, w) \in E(G)\}$. Let $N[G; v] = N(G; v) \cup \{v\}$, and let $N[G; V'] = \bigcup_{v \in V'} N[G; v]$ for a vertex-subset $V' \subseteq V(G)$.

2.2 Definitions for TOKEN JUMPING

Let I_i and I_j be two independent sets of the same cardinality in a graph $G = (V, E)$. We say that I_i and I_j are *adjacent* if there exists exactly one pair of vertices u and v such that $I_i \setminus I_j = \{u\}$ and $I_j \setminus I_i = \{v\}$, that is I_j can be obtained from I_i by *moving* the token on a vertex $u \in I_i$ to another vertex $v \in V \setminus I_i$. We remark that the tokens are unlabeled, while the vertices in a graph are labeled.

A *reconfiguration sequence* between two independent sets I and I' of G is a sequence $\langle I_1, I_2, \dots, I_\ell \rangle$ of independent sets of G such that $I_1 = I$, $I_\ell = I'$, and I_{i-1} and I_i are adjacent for $i = 2, 3, \dots, \ell$. We say that two independent sets I and I' are *reconfigurable* each other if there exists a reconfiguration sequence between I and I' . Clearly, any two adjacent independent sets are reconfigurable each other. The *length* of a reconfiguration sequence \mathcal{S} is defined as the number of independent sets contained in \mathcal{S} . For example, the length of the reconfiguration sequence in Fig. 1 is 6.

The TOKEN JUMPING problem is to determine whether two given independent sets I_0 and I_r of a graph G are reconfigurable each other. We may assume without loss of generality that $|I_0| = |I_r|$; otherwise the answer is clearly “no.” Note that TOKEN JUMPING is a decision problem asking the existence of a reconfiguration sequence between I_0 and I_r , and hence it does not ask an actual reconfiguration sequence. We always denote by I_0 and I_r the *initial* and *target* independent sets of G , respectively, as an instance of TOKEN JUMPING.

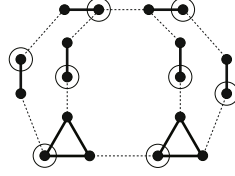


Fig. 2. Graph consisting of token triangles and token edges, where link edges are depicted by thin dotted lines and the vertices in a standard independent set (namely, with tokens) are surrounded by circles

2.3 PSPACE-Completeness

As we have mentioned in Introduction, Bonsma and Cereceda [2] showed that ISRECONF under the TS rule is PSPACE-complete, and their result indeed implies the PSPACE-completeness of TOKEN JUMPING. We here formally explain this fact, as in the following theorem.

Theorem 1. *The TOKEN JUMPING problem is PSPACE-complete for planar graphs with maximum degree three.*

Proof. The problem is clearly in PSPACE, and hence we show that TOKEN JUMPING is PSPACE-hard for planar graphs with maximum degree three.

Bonsma and Cereceda [2] showed that ISRECONF under the TS rule is PSPACE-complete even for very restricted instances, defined as follows. Every vertex of a graph G is a part of exactly one of *token triangles* (i.e., copies of K_3) and *token edges* (i.e., copies of K_2), as illustrated in Fig. 2. Token triangles and token edges are all mutually disjoint, and joined together by edges called *link edges*. Moreover, $\Delta(G) = 3$ and G has a planar embedding such that every token triangle forms a face. We say that an independent set I of G is *standard* if each of token triangles and token edges contains exactly one token (vertex) in I . The ISRECONF problem under the TS rule remains PSPACE-complete even if G is such a restricted graph and both I_0 and I_r are standard independent sets [2].

Note that a standard independent set of G is a maximal independent set. Then, even under the TJ rule (i.e., in TOKEN JUMPING), each token can jump only to its adjacent vertex. Therefore, I_0 and I_r are reconfigurable each other under the TS rule if and only if they are reconfigurable each other under the TJ rule. Thus, the result follows. \square

3 W[1]-Hardness

In this section, we give the hardness result as in the following theorem.

Theorem 2. *The TOKEN JUMPING problem is W[1]-hard when parameterized by the number of tokens.*



Fig. 3. Image of our reduction, where the vertices in independent sets are depicted by large black circles (tokens)

Proof. We give an FPT-reduction from INDEPENDENT SET parameterized by the solution size to TOKEN JUMPING parameterized by the number of tokens. Given a graph G' and a parameter t' , the INDEPENDENT SET *problem parameterized by the solution size* is to determine whether there is an independent set I of G' such that $|I| \geq t'$. This problem is known to be W[1]-hard [16, p. 213].

We now construct the corresponding instance of TOKEN JUMPING. (See also Fig. 3.) Let G be the graph which consists of G' and a complete bipartite graph $K_{t'+1, t'+1}$. Therefore, G consists of two connected components. Let $\{U, W\}$ be the bipartition of $V(K_{t'+1, t'+1})$. Let $I_0 = U$ and $I_r = W$, then $|I_0| = |I_r| = |U| = |W| = t' + 1$. Therefore, the parameter (*i.e.*, the number of tokens) for TOKEN JUMPING is $t = t' + 1$. Clearly, the corresponding instance can be constructed in time $O(n(G') + t'^2)$.

To complete the FPT-reduction, we now show that G' has an independent set I with $|I| \geq t'$ if and only if I_0 and I_r are reconfigurable each other.

Suppose that G' has an independent set I with $|I| \geq t'$. Then, there is a reconfiguration sequence between I_0 and I_r , as follows: first move t' ($= t - 1$) tokens from U to the vertices in I one by one; then move the last token on the vertex in U to any vertex in W ; and move t' tokens from I to W one by one. Therefore, I_0 and I_r are reconfigurable each other.

Conversely, suppose that I_0 and I_r are reconfigurable each other, and hence there is a reconfiguration sequence \mathcal{S} between I_0 and I_r . Since $K_{t'+1, t'+1}$ is a complete bipartite graph, G has no independent set I' such that both $I' \cap U \neq \emptyset$ and $I' \cap W \neq \emptyset$ hold. Therefore, since we can move only one token at a time, \mathcal{S} must contain an independent set I_q of G such that both $I_q \cap U = \{u\}$ and $I_q \cap W = \emptyset$ hold. Then, all vertices in $I_q \setminus \{u\}$ are contained in the component G' of G , and they must form an independent set of G' . Since $|I_q \setminus \{u\}| = t - 1 = t'$, there exists an independent set $I = I_q \setminus \{u\}$ of G' such that $|I| = t'$. \square

4 FPT Algorithms

Theorem 2 implies that TOKEN JUMPING admits no FPT algorithm when parameterized only by the number of tokens unless $\text{FPT} = \text{W}[1]$. Therefore, in this section, we give an FPT algorithm for general graphs when parameterized by both the number of tokens and the maximum degree. Recall that TOKEN JUMPING remains PSPACE-complete even for planar graphs with bounded maximum degree.

In Section 4.1, we first give an FPT algorithm which simply solves TOKEN JUMPING for general graphs. We then show in Section 4.2 that our FPT algorithm can be modified so that it finds an actual reconfiguration sequence with the minimum length.

4.1 TOKEN JUMPING

The main result of this subsection is the following theorem.

Theorem 3. *Let G be a graph whose maximum degree is bounded by a fixed constant d . Let I_0 and I_r be two independent sets of G such that $|I_0| = |I_r| \leq t$ for a fixed constant t . Then, one can determine whether I_0 and I_r are reconfigurable each other in time $O((3td)^{2t})$.*

In this subsection, we give such an algorithm as a proof of Theorem 3. We first show in Lemma 1 that, if a graph G has at least $3t(d+1)$ vertices, then I_0 and I_r are always reconfigurable each other. Therefore, one can know that the answer is always “yes” if $n(G) \geq 3t(d+1)$, and hence it suffices to deal with a graph having less than $3t(d+1)$ vertices. For such a graph, we then show in Lemma 2 that there is an $O((3td)^{2t})$ -time algorithm that determines whether I_0 and I_r are reconfigurable each other.

We first show that any two independent sets are reconfigurable each other if the graph has a sufficiently large number of vertices, as in the following lemma.

Lemma 1. *Let G be a graph with $\Delta(G) \leq d$, and let I_i and I_j be an arbitrary pair of independent sets of G such that $|I_i| = |I_j| \leq t$. Then, I_i and I_j are reconfigurable each other if $n(G) \geq 3t(d+1)$.*

Proof. Suppose that $n(G) \geq 3t(d+1)$. To prove the lemma, we show that there exists a reconfiguration sequence between I_i and I_j .

Let G^- be the graph obtained from G by deleting all vertices in $N[G; I_i] \cup N[G; I_j]$. Since all neighbors of the vertices in $I_i \cup I_j$ have been deleted from G , no vertex in G^- is adjacent with any vertex in $I_i \cup I_j$. Therefore, if G^- has an independent set I_k with $|I_k| \geq t$, then there is a reconfiguration sequence between I_i and I_j , as follows: move all tokens on the vertices in I_i to the vertices in I_k one by one; and move all tokens on the vertices in I_k to the vertices in I_j one by one.

To complete the proof, we thus show that G^- has an independent set I_k with $|I_k| \geq t$ if $n(G) \geq 3t(d+1)$. Since $\Delta(G) \leq d$, we clearly have $|N[G; v]| \leq d+1$ for every vertex v in G . Since $|I_i| \leq t$, we thus have

$$|N[G; I_i]| \leq \sum_{v \in I_i} |N[G; v]| \leq t(d+1).$$

Similarly, we have $|N[G; I_j]| \leq t(d+1)$. Therefore,

$$n(G^-) \geq n(G) - |N[G; I_i]| - |N[G; I_j]| \geq t(d+1). \quad (1)$$

We now suppose for a contradiction that $|I_{\max}| < t$ holds for a maximum independent set I_{\max} of G^- . Then, we have

$$|N[G^-; I_{\max}]| \leq \sum_{v \in I_{\max}} |N[G; v]| < t(d+1),$$

and hence by Eq. (1)

$$n(G^-) - |N[G^-; I_{\max}]| \geq 1.$$

Therefore, the graph obtained from G^- by deleting all vertices in $N[G^-; I_{\max}]$ is non-empty, and hence we can add at least one vertex to I_{\max} . This contradicts the assumption that I_{\max} is a maximum independent set of G^- . Therefore, $|I_{\max}| \geq t$, and hence G^- has an independent set I_k with $|I_k| \geq t$. \square

We then give an FPT algorithm for the case where a given graph G has only a constant number of vertices, as in the following lemma.

Lemma 2. *Suppose that $n(G) < 3t(d+1)$. Then, there is an $O((3td)^{2t})$ -time algorithm which determines whether I_0 and I_r are reconfigurable each other.*

Proof. We give such an algorithm. For a graph G and a constant $t' = |I_0| = |I_r|$ ($\leq t$), we construct a *configuration graph* $\mathcal{C} = (\mathcal{V}, \mathcal{E})$, as follows:

- (i) each node in \mathcal{C} corresponds to an independent set of G with cardinality exactly t' ; and
- (ii) two nodes in \mathcal{C} are joined by an edge if and only if the corresponding two independent sets are adjacent.

For an independent set I of G with $|I| = t'$, we always denote by w_I the node of \mathcal{C} corresponding to I . Clearly, two independent sets I_0 and I_r are reconfigurable each other if and only if there is a path in \mathcal{C} between w_{I_0} and w_{I_r} .

Notice that G has at most the number $\binom{n(G)}{t'}$ of distinct independent sets with cardinality exactly t' . Since $t' \leq t$, we thus have

$$|\mathcal{V}| \leq \binom{n(G)}{t'} < \binom{3t(d+1)}{t'} = O((3td)^t).$$

The configuration graph \mathcal{C} above can be constructed in time $O(|\mathcal{V}|^2)$. Furthermore, by the breadth-first search on \mathcal{C} starting from the node w_{I_0} , one can determine whether \mathcal{C} has a path from w_{I_0} to w_{I_r} in time $O(|\mathcal{V}| + |\mathcal{E}|) = O(|\mathcal{V}|^2)$. In this way, our algorithm runs in time $O(|\mathcal{V}|^2) = O((3td)^{2t})$ in total. \square

Lemmas 1 and 2 complete the proof of Theorem 3. \square

4.2 Shortest Reconfiguration Sequence

We now give an FPT algorithm which finds an actual reconfiguration sequence with the minimum length.

Theorem 4. *Let G be a graph whose maximum degree is bounded by a fixed constant d . Let I_0 and I_r be two independent sets of G such that $|I_0| = |I_r| \leq t$ for a fixed constant t . Then, one can find a shortest reconfiguration sequence between I_0 and I_r in time $O((4td)^{2t} + n(G) + m(G))$ if there exists.*

We give such an algorithm as a proof of Theorem 4. Let $t' = |I_0| = |I_r| \leq t$. Although our algorithm is based on the proofs in Section 4.1, the number of vertices for the graph classification is slightly changed from $3t(d+1)$ to $4t(d+1)$; this yields that the base of the running time becomes 4 in Theorem 4.

We first consider the case where $n(G) < 4t(d+1)$.

Lemma 3. *Suppose that $n(G) < 4t(d+1)$. Then, one can find a shortest reconfiguration sequence between I_0 and I_r in time $O((4td)^{2t})$ if there exists.*

Proof. As in the proof of Lemma 2, we construct the configuration graph $\mathcal{C} = (\mathcal{V}, \mathcal{E})$ for G and t' in time

$$O(|\mathcal{V}|^2) = O\left(\binom{4t(d+1)}{t'}^2\right) = O((4td)^{2t}).$$

Recall that the node set of \mathcal{C} corresponds to *all* independent sets in G of cardinality exactly t' . Therefore, a shortest reconfiguration sequence between two independent sets I_0 and I_r corresponds to a shortest path in \mathcal{C} between the two nodes w_{I_0} and w_{I_r} . By the breadth-first search on \mathcal{C} starting from w_{I_0} , one can find a shortest path in \mathcal{C} in time $O(|\mathcal{V}| + |\mathcal{E}|) = O(|\mathcal{V}|^2)$ if there exists. Therefore, if $n(G) < 4t(d+1)$, one can find a shortest reconfiguration sequence in time $O(|\mathcal{V}|^2) = O((4td)^{2t})$. \square

We then consider the case where $n(G) \geq 4t(d+1)$. Notice that, since $n(G)$ is not bounded by a fixed constant, we cannot directly construct the configuration graph \mathcal{C} for G and t' in this case. However, we will prove that only a subgraph of \mathcal{C} having a constant number of nodes is sufficient to find a shortest reconfiguration sequence.

Lemma 1 ensures that there always exists a reconfiguration sequence between I_0 and I_r in this case. Furthermore, in the proof of Lemma 1, we proposed a reconfiguration sequence \mathcal{S}' between I_0 and I_r such that every token is moved exactly twice. Although this is not always a shortest reconfiguration sequence, the minimum length of a reconfiguration sequence between I_0 and I_r can be bounded by the length of \mathcal{S}' , that is, $2t'$.

Let G^- be the graph obtained from G by deleting all vertices in $N[G; I_0] \cup N[G; I_r]$. Then, by the counterpart of Eq. (1) we have $n(G^-) \geq 2t(d+1)$, and hence G^- has an independent set I'_k such that $|I'_k| = 2t' (\leq 2t)$. We now give the following lemma.

Lemma 4. *There exists a shortest reconfiguration sequence \mathcal{S} between I_0 and I_r such that $I \subseteq I_0 \cup I'_k \cup I_r$ for all independent sets I in \mathcal{S} .*

Proof. Let $\mathcal{S}^* = \langle I_0^*, I_1^*, \dots, I_\ell^* \rangle$ be an arbitrary shortest reconfiguration sequence between $I_0 = I_0^*$ and $I_r = I_\ell^*$. Then, the proof of Lemma 1 implies that $\ell \leq 2t'$, as we have mentioned above. Note that some independent sets in \mathcal{S}^* may contain vertices in $V(G) \setminus (I_0 \cup I_k' \cup I_r)$. Let

$$V(I_0, I_r; \mathcal{S}^*) = \bigcup_{1 \leq i \leq \ell-1} (I_i^* \setminus (I_0 \cup I_r)),$$

that is, $V(I_0, I_r; \mathcal{S}^*)$ is the set of all vertices that are not in $I_0 \cup I_r$ but appear in the reconfiguration sequence \mathcal{S}^* . Since $\ell \leq 2t'$ and $|I_{i+1}^* \setminus I_i^*| = 1$ for all i , $0 \leq i \leq \ell - 1$, we have $|V(I_0, I_r; \mathcal{S}^*)| < \ell \leq 2t'$.

Therefore, since $|I_k'| = 2t'$, one can replace all vertices in $V(I_0, I_r; \mathcal{S}^*)$ with distinct vertices in I_k' ; let \mathcal{S} be the resulting sequence. Recall that I_k' is an independent set of G^- , and hence no vertex in I_k' is adjacent with any vertex in $I_0 \cup I_r$. Therefore, \mathcal{S} is a reconfiguration sequence between I_0 and I_r . Note that any independent set I in \mathcal{S} satisfies $I \subseteq I_0 \cup I_k' \cup I_r$. Furthermore, the length of \mathcal{S} is equal to that of \mathcal{S}^* , and hence \mathcal{S} is a shortest reconfiguration sequence. \square

We now give the following lemma, which completes the proof of Theorem 4.

Lemma 5. *Suppose that $n(G) \geq 4t(d+1)$. Then, one can find a shortest reconfiguration sequence between I_0 and I_r in time $O((4t)^{2t} + n(G) + m(G))$.*

Proof. We first remark that an independent set I_k' of G^- with $|I_k'| = 2t' (\leq 2t)$ can be found in time $O(n(G) + m(G))$ by the following simple greedy algorithm: initially, let $I_k' = \emptyset$; choose an arbitrary vertex v in G^- , and add v to I_k' ; delete all vertices in $N[G^-; v]$ from G^- , and repeat. Recall that $n(G^-) \geq 2t(d+1)$ and $|N[G^-; v]| \leq d+1$ for every vertex v in G^- . Therefore, this greedy algorithm always finds an independent set I_k' with $|I_k'| = 2t'$.

Let G_{0kr} be the subgraph of G induced by the vertex-subset $I_0 \cup I_k' \cup I_r$. Notice that $n(G_{0kr}) = |I_0 \cup I_k' \cup I_r| \leq 4t'$. Let \mathcal{C}_{0kr} be the configuration graph for G_{0kr} and the constant t' . Since G_{0kr} is an induced subgraph of G , any independent set I of G_{0kr} is an independent set of G . Then, Lemma 4 ensures that there exists a shortest reconfiguration sequence \mathcal{S} between I_0 and I_r such that every independent set I in \mathcal{S} is an independent set of G_{0kr} . Therefore, such a shortest reconfiguration sequence \mathcal{S} between I_0 and I_r can be found as a shortest path in \mathcal{C}_{0kr} between the two nodes w_{I_0} and w_{I_r} . This can be done in time $O((4t)^{2t})$, because the number of nodes in \mathcal{C}_{0kr} can be bounded by $\binom{n(G_{0kr})}{t'} = O((4t)^t)$.

In this way, if $n(G) \geq 4t(d+1)$, one can find a shortest reconfiguration sequence between I_0 and I_r in time $O((4t)^{2t} + n(G) + m(G))$ in total. \square

5 Concluding Remarks

In this paper, we mainly gave three results for the parameterized complexity of TOKEN JUMPING. We remark that the running time of each of our FPT algorithms is just a single exponential with respect to the number of tokens; furthermore, the parameter d of maximum degree does not appear in the exponent.

We also remark that the problem parameterized only by the number of tokens is in the class XP, that is, the problem can be solved in polynomial time if the number t of tokens is a fixed constant. To see this, consider the following algorithm: construct the configuration graph \mathcal{C} for a given graph G and the fixed constant t ; and find a (shortest) path in \mathcal{C} . Since the number of nodes in \mathcal{C} can be bounded by $\binom{n}{t}$, the problem can be solved in time $O(n^{2t})$, where $n = n(G)$. Therefore, the problem for a fixed number of tokens can be solved in polynomial time, while the problem remains PSPACE-complete for a fixed maximum degree.

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